The Performance and Validation of GPM's Falling Snow Retrieval Algorithms

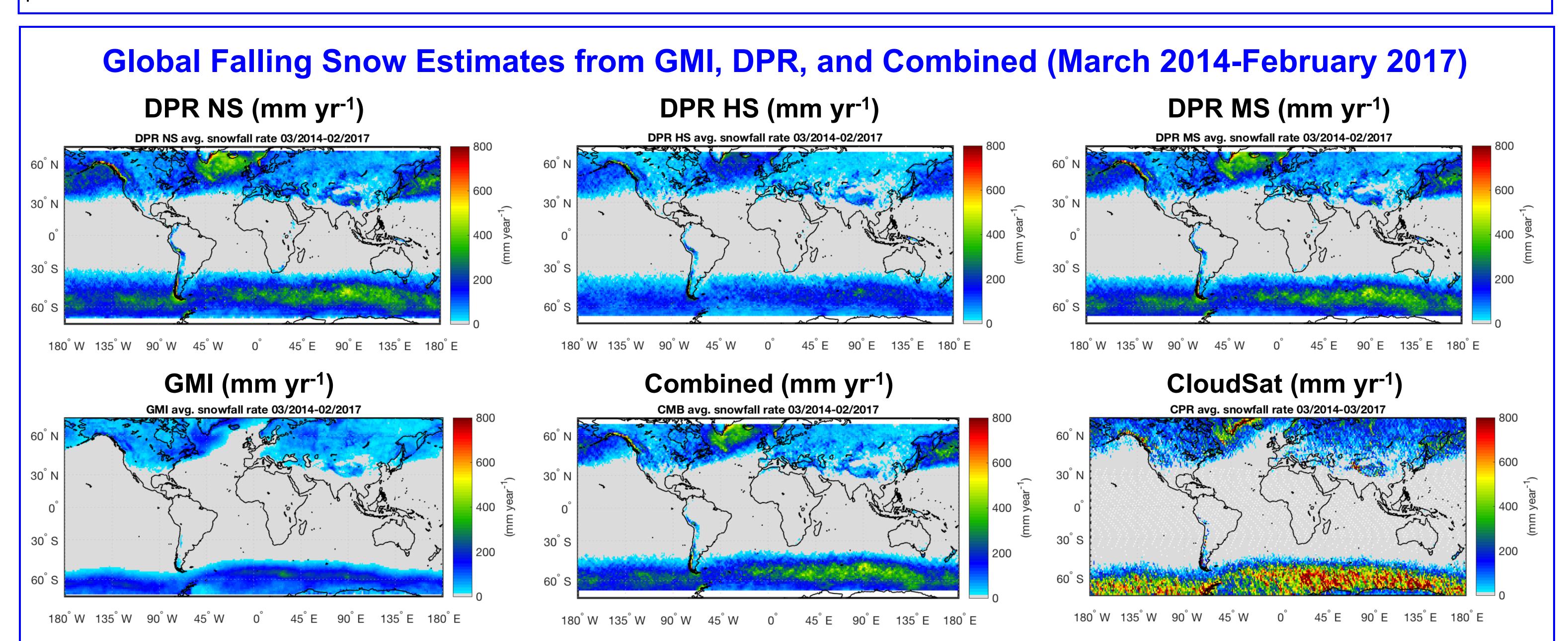
Gail Skofronick-Jackson¹, Joe Munchak¹, Mark Kulie², Norm Wood³, Lisa Milani²

¹Mesoscale Processes Branch, Code 612, NASA Goddard Space Flight Center, Greenbelt, MD, USA, Gail.S.Jackson@nasa.gov ²Michigan Technological University, ³University of Wisconsin

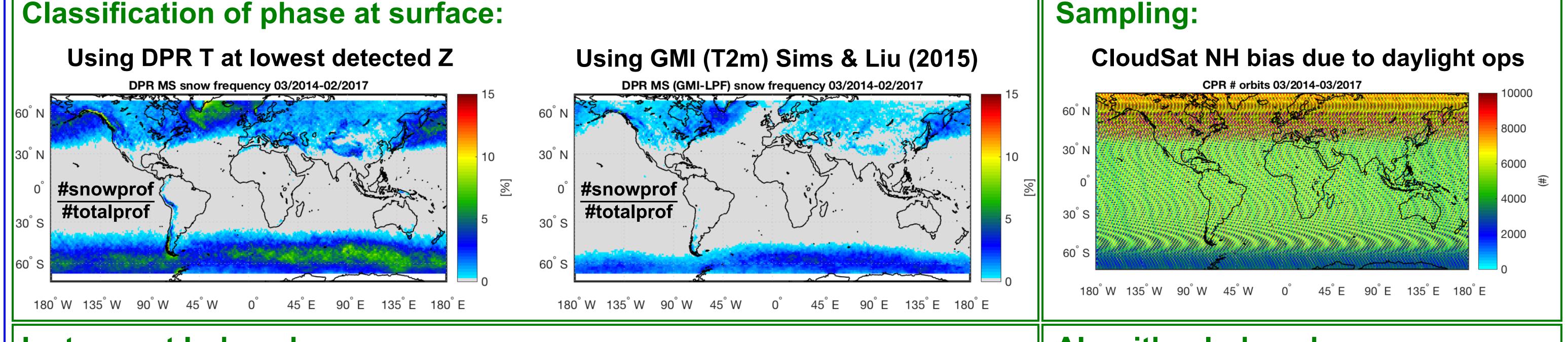
Introduction:

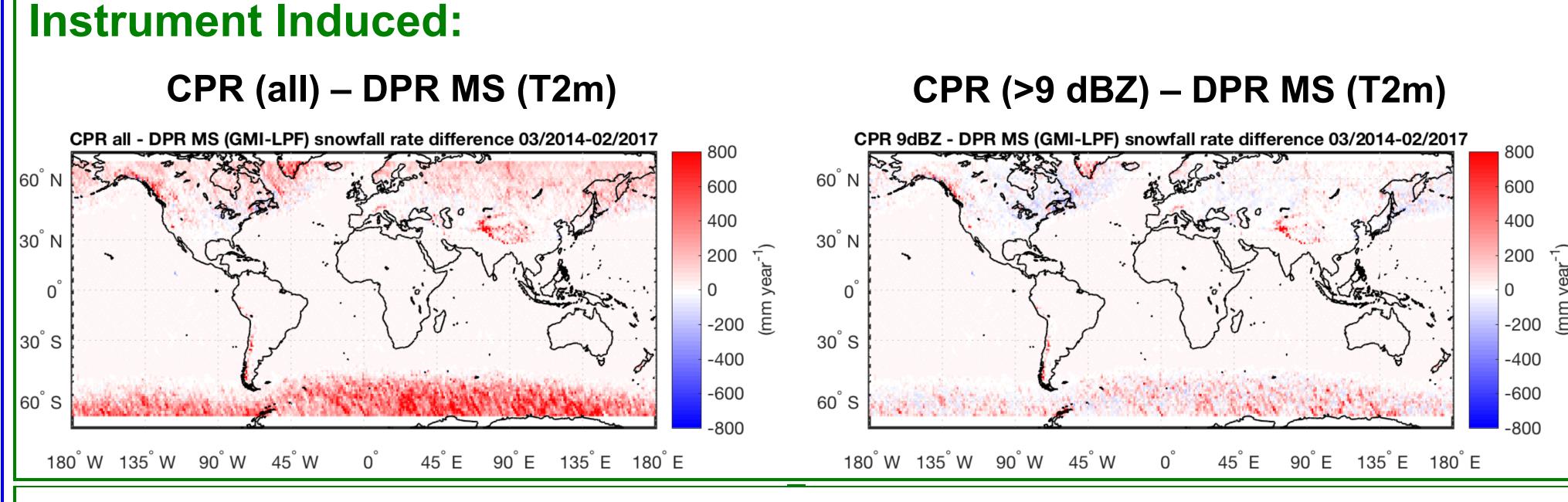
Precipitation falling in the form of snow is vitally important for society and the Earth's climate, geology, agriculture, and ecosystem. In some parts of the world, snow is the dominant precipitation type and relied upon year round for fresh water. The Global Precipitation Measurement (GPM) mission (launched 2014 in a partnership between NASA and JAXA) was specifically designed to remotely sense (estimate) both liquid rain and falling snow. This poster describes **preliminary results and performance evaluations of falling snow estimates** using the GPM Microwave Imager (GMI) and the Dual-frequency Precipitation Radar (DPR) on board GPM. All snow estimates are in liquid equivalent units.

To compare GPM falling snow estimates with other sources of falling snow estimates, such as from CloudSat, we must ensure that the analysis is done properly as there are several factors that limit raw-product comparisons. These include those induced by: **phase classification, sampling, instrumentation** (resolution/sensitivity), and algorithm differences. Classification refers to the method used to assign rain or snow at the surface. Sampling due to differing swath widths and orbits causes additional disparities between the products. The instruments have different design features, most notably minimum detectable reflectivity and frequency sensitivities. Algorithm assumptions lead to dissimilarities that are more difficult to reconcile. A discussion of these four factors is also presented.



Challenges in Comparing GPM and CloudSat Falling Snow Estimates





Acknowledgments

We thank the GPM algorithm developers and the Precipitation Processing System for retrieval estimates and data processing. Funding for this work comes from NASA Headquarters Ramesh Kakar for PIs Skofronick-Jackson (8th PMM Science Team), Munchak/Kulie/Wood, (9th Science team). Milani is funded through Kulie's PMM grant and via other sources. The GPM Project also supports Skofronick-Jackson.

Algorithm Induced: Instrument Snow Mean Occurrence **Snow Rate Table** (%)(mm/day) data CloudSat 0.1229 2.422 uses (native res) **DPR** DPR-NS 0.262 0.0401 T2m DPR-MS 0.262 0.0402 0.199 0.0208 DPR-HS 2.879 0.1212 CloudSat = $\|(5-pixel)\|$ CloudSat 3.516 0.1208 (15-pixel) 0.276 0.0556 CloudSat (15-pixel,

Despite yielding a similar occurrence, a cutoff of 8-9 dBZ for CPR yields a mean snowfall rate 30-40% higher than DPR-MS. The algorithm differences lead to higher snowfall rates from CPR than DPR, even when the same events are being observed.